# 1. Product Description

NX-ERA Series is a powerful and complete Programmable Logic Controller (PLC) with unique and innovative features. Due to its flexibility, smart design, enhanced diagnostics capabilities and modular architecture, NX-ERA is suitable for control systems ranging from medium to high-end large applications. Finally, its compact size, high density of points per module and superior performance, allow NX-ERA Series to be applied in small automation systems with high performance requirements, such as manufacturing applications and industrial machines.

The Series has a wide variety of CPUs, I/O and communication modules with features to fit requirements in different kinds of applications. The options available cover from standard automation systems, high-availability applications where redundancy is a major requirement, distributed applications to functional safety systems.

The NX5100 and NX5101 modules are devices of slave head type for MODBUS TCP networks, allowing the user to use all I/O modules of NX-ERA Series. Finally, NX-ERA Series has some innovative features for diagnostics and maintenance, such as Electronic Tag on Display, Easy Plug System and One Touch Diag.





Its main features are:

- MODBUS TCP protocol for communication of I/O data
- Ethernet interface 10/100 Mbps with auto crossover
- Integrated power supply
- Integrated Digital Inputs and Outputs (only in NX5101)
- Configurable IP Address through LCD or web page
- Ability to use up to 22 I/O modules in a single rack (only in NX5100)
- Support NX-ERA Series (NX) I/O modules
- Support NX-ERA Jet Series (NJ) I/O modules
- Support hot swap I/O modules (only in NX5100)
- Integrated web page for diagnostics, IP address configuration and firmware update
- Diagnostics and states of local operation via LEDs (only in NX5100)
- Diagnostics and states of local operation via display
- Diagnostics and states of remote operation via web page and MODBUS TCP protocol
- One Touch Diag
- Free of moving parts (fans, coolers, etc.)

# 2. Ordering Information

#### 2.1. Included Items

The NX5100 product package contains the following items:

- NX5100 module
- 6-terminal connector

The NX5101 product package contains the following items:

- NX5101 module
- 12-terminal connector
- 18-terminal connector

## 2.2. Product Code

The following products must be purchased separately when necessary:

| Code   | Description   |
|--------|---|
| NX5100 | MODBUS TCP Head   |
| NX5101 | MODBUS TCP Head without hot swap, with 14 digital inputs and 10 digital outputs |

Table 1: Product Code

## 3. Related Products

The following products must be purchased separately when necessary:

| Code   | Description                         |  |
|--------|-------------------------------------|--|
| NX9000 | 8-Slot Backplane Rack               |  |
| NX9001 | 12-Slot Backplane Rack              |  |
| NX9002 | 16-Slot Backplane Rack              |  |
| NX9003 | 24-Slot Backplane Rack              |  |
| NX9010 | 8-Slot Backplane Rack (No Hot Swap) |  |
| NX9020 | 2-Slot base for panel assembly      |  |
| NX9404 | 6-terminal connector with fixing    |  |
| NX9405 | 12-terminal connector with fixing   |  |
| NX9406 | 18-terminal connector with fixing   |  |
| NX9202 | RJ45-RJ45 2 m Cable                 |  |
| NX9205 | RJ45-RJ45 5 m Cable                 |  |
| NX9210 | RJ45-RJ45 10 m Cable                |  |
| MT8500 | MasterTool IEC XE                   |  |

Table 2: Related products

#### **Notes:**

**NX9010**: NX9010 rack model doesn't support IO module's hot swap. It neither supports double width modules, as NX2020.

**NX9020:** The NX9020 accessory is only compatible with the NX5101.

**MT8500:** MasterTool IEC XE is available in four different versions: LITE, BASIC, PROFESSIONAL and ADVANCED. For more details, please check MasterTool IEC XE User Manual – MU299609.

## 4. Innovative Features

NX-ERA Series brings to the user many innovations regarding utilization, supervision and system maintenance. These features were developed focusing a new concept in industrial automation.



One Touch Diag: One Touch Diag is an exclusive feature that NX-ERA Series brings to PLCs. With this new concept, the user can check diagnostic information of any module present in the system directly on CPU's graphic display with one single press in the diagnostic switch of the respective module. OTD is a powerful diagnostic tool that can be used offline (without supervisor or programmer), re-ducing maintenance and commissioning times.

ETD – Electronic Tag on Display: Another exclusive feature that NX-ERA Series brings to PLCs is the Electronic Tag on Display. This new functionality brings the process of checking the tag names of any I/O pin or module used in the system directly to the CPU's graphic display. Along with this information, the user can check the description, as well. This feature is extremely useful during maintenance and troubleshooting procedures.

DHW – Double Hardware Width: NX-ERA Series modules were designed to save space in user cabi- nets or machines. For this reason, NX-ERA Series delivers two different module widths: Double Width (two backplane rack slots are required) and Single Width (only one backplane rack slot is required). This concept allows the use of compact I/O modules with a high-density of I/O points along with complex modules, like CPUs, fieldbus masters and power supply modules.



iF Product Design Award 2012: NX-ERA Series was the winner of iF Product Design Award 2012 in industry + skilled trades group. This award is recognized internationally as a seal of quality and excellence, considered the Oscars of the design in Europe..

# 5. Product Features

## 5.1. General Features

|   | NX5100   | NX5101                                    |  |
|---|--|---|--|
| Backplane Rack Occupation               | 2 Sequential Positions   |   |  |
| One Touch Diag (OTD)                    |  |   |  |
| Electronic Tag on Display (ETD)         |  |   |  |
| Status and diagnostic indication        | Graphic display, LEDs, web pages, Head internal memory and MODBUS TCP protocol |   |  |
| Hot Swap Support                        |  | 4.  |  |
| Maximum I/O modules                     | 22   | ro  |  |
| Isolation                               |  |   |  |
| Logic to Earth Protection 🖨             | 1750 Vdc / 1 minute (1250 Vac / 1 minute)                                      | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |  |
| Logic to Ethernet interface             | 2000 Vdc / 1 minute (1500 Vac / 1 minute)                                      | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |  |
| Ethernet Interface to Earth Protection  | 1750 Vdc / 1 minute (1250 Vac / 1 minute)                                      | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |  |
| Maximum Dissipation                     | 4 W  |   |  |
| IP Level                                | IP 20  |   |  |
| Operating Temperature                   | 0 to 60 °C   |   |  |
| Storage Temperature                     | -25 to 75 °C   |   |  |
| Operation and Storage Relative Humidity | 5% to 96%, non-condensing  |   |  |
| Conformal Coating                       | ✓  | ✓   |  |
| Module dimensions (W x H x D)           | 36.00 x 114.63 x 115.30 mm   |   |  |
| Package dimensions (W x H x D)          | 44.00 x 122.00 x 147.00 mm   |   |  |
| Weight                                  | 350 g  |   |  |
| Weight with Package                     | 400 g  |   |  |

Table 3: General Features

#### Note:

Conformal Coating: Conformal coating protects the electronic components inside the product from moisture, dust and other harsh elements to electronic circuits.

# 5.2. Standards and Certifications

| Standards and Certifications<br>NX5100 / NX5101 |   |  |
|---|---|--|
| IEC   | 61131-2: Industrial-process measurement and control - Programmable controllers - Part 2: Equipment requirements and tests |  |
| ONV.COM/AF                                      | DNV Type Approval – DNV-CG-0339 (TAA000013D) (Except NX5101)  |  |
| CE  | 2014/30/EU (EMC)<br>2014/35/EU (LVD)<br>2011/65/EU and 2015/863/EU (ROHS)   |  |
| UK  | S.I. 2016 No. 1091 (EMC)<br>S.I. 2016 No. 1101 (Safety)<br>S.I. 2012 No. 3032 (ROHS)                                      |  |
| C UL US   | UL/cUL Listed – UL 61010-1<br>UL 61010-2-201 (file E473496)   |  |
| EAC   | TR 004/2011 (LVD)<br>CU TR 020/2011 (EMC)   |  |

Table 4: Standards and Certifications

## 5.3. NET 1

|                      | NX5100, NX5101                               |
|----------------------|--|
| Connector            | Shielded female RJ45                         |
| Auto crossover       | Yes  |
| Maximum cable length | 100 m  |
| Cable type           | UTP or ScTP, category 5                      |
| Baud rate            | 10/100 Mbps                                  |
| Physical layer       | 10/100 BASE-TX                               |
| Data link layer      | LLC (logical link control)                   |
| Network layer        | IP (internet protocol)                       |
| Transport layer      | TCP (Transmission Control Protocol)          |
|                      | UDP (User Datagram Protocol)                 |
| Application layer    | MODBUS TCP Server                            |
|                      | HTTP Server                                  |
| Diagnostics          | LEDs – green (speed), yellow (link/activity) |

Table 5: NET1 Features

# 5.4. Power Supply

|  | NX5100                                    |
|--|---|
| Nominal Input Voltage                  | 24 Vdc                                    |
| Maximum Output Power                   | 15W @ 60 °C                               |
| •                                      | 20W @ 50 °C                               |
| Maximum Output Current                 | 3 A                                       |
| Input Voltage                          | 19.2 to 30 Vdc                            |
| Maximum Input Current (in-rush)        | 30 A                                      |
| Maximum Input Current                  | 1.4 A                                     |
| Maximum input voltage interruption     | 10 ms @ 24 Vdc                            |
| Isolation                              |   |
| Input to Output                        | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Input to Earth Protection ⊕            | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |
| Input to Functional Earth              | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Wire Gauge                             | 0.5 mm <sup>2</sup>                       |
| Reverse polarity protection            | Yes                                       |
| Internal Resettable fuse               | Yes                                       |
| Short-circuit protection on the output | Yes                                       |
| Over Current Protection                | Yes                                       |

Table 6: Power Supply Features (NX5100)

#### Note:

**Maximum output power**: To use the extended maximum output power, some conditions must be respected: use of NX-ERA Jet I/O modules only; reduction of maximum operating temperature; do not perform a hot swap of I/O modules, at the risk of affecting the system operation; modules NJ6000, NJ6010 and NJ6100 need to have revision AB or greater.

|  | NX5101                                     |  |
|--|--|--|
| Nominal Input Voltage                  | 24 Vdc                                     |  |
| Maximum Output Power                   | 10 W                                       |  |
| Maximum Output Current                 | 2 A  |  |
| Input Voltage                          | 19.2 to 30 Vdc                             |  |
| Maximum Input Current (in-rush)        | 40 A                                       |  |
| Maximum Input Current                  | 1 A  |  |
| Maximum input voltage interruption     | 1 ms @ 24 Vdc                              |  |
| Isolation                              |  |  |
| Input to Output                        | 1500 Vdc / 1 minute (1000 Vac / 1 minute)  |  |
| Input to Earth Protection ⊕            | 1500 Vdc / 1 minute (1000 Vac / 1 minute() |  |
| Wire Gauge                             | $0.5~\mathrm{mm}^2$                        |  |
| Reverse polarity protection            | Yes  |  |
| Internal Resettable fuse               | No   |  |
| Short-circuit protection on the output | No   |  |
| Over Current Protection                | No   |  |

Table 7: Power Supply Features (NX5101)

# 5.5. Digital Inputs

|                                   | NX5101  |  |  |
|-----------------------------------|---|--|--|
| -                                 | 2 .2 .2 .2 .2 .   |  |  |
| Input type                        | Type 1 sink   |  |  |
| Inputs number                     | 14  |  |  |
| Connector configuration           | I0, I1, I2, I3, I4, I5, I6, I7, I8, I9, I10, I11, I12 and |  |  |
| Connector configuration           | I13   |  |  |
|                                   | 24 Vdc  |  |  |
| Input Voltage                     | 15 to 30 Vdc for logic level 1                            |  |  |
|                                   | 0 to 5 Vdc for logic level 0                              |  |  |
| Input impedance                   | 1.85 kΩ for I0 to I3                                      |  |  |
|                                   | $4.95 \text{ k}\Omega$ for I4 to I13                      |  |  |
| Maximum Input Current             | 6.2 mA @ 30 Vdc   |  |  |
| Input status indication           | Yes   |  |  |
| Input update time                 | 1 ms  |  |  |
| Input filter                      | 100 μs – by hardware                                      |  |  |
|                                   | 2 ms to 255 ms – by software                              |  |  |
| Isolation                         |   |  |  |
| Input to Logic                    | 2000 Vdc / 1 minute (1500 Vac / 1 minute)                 |  |  |
| Input to Outputs                  | 1500 Vdc / 1 minute (1000 Vac / 1 minute)                 |  |  |
| Input to Ethernet                 | 2000 Vdc / 1 minute (1500 Vac / 1 minute)                 |  |  |
| Inputs I0 for I3 to power supply  | It has not  |  |  |
| Inputs 14 for I13 to power supply | 1500 Vdc / 1 minute (1000 Vac / 1 minute)                 |  |  |
| Input to protection Earth 🖨       | 1500 Vdc / 1 minute (1000 Vac / 1 minute)                 |  |  |

Table 8: Digital Inputs Features

#### Note:

**Input** filter: Filter sampling is performed in the MainTask (or update function), so it is recommended to use multiple values of the task interval.

# 5.6. Transistor Digital Output

|                             | NX5101  |
|-----------------------------|---|
| Outputs number              | 10  |
| Connector configuration     | Q0, Q1, Q2, Q3, Q4, Q5, Q6, Q7, Q8 and Q9         |
| Maximum current             | 0.5 A @ 30 Vdc per output Q0 to Q3                |
|                             | 2 A @ 30 Vdc total for Q0 to Q3                   |
|                             | 1.5 A @ 30 Vdc per output Q4 to Q9                |
|                             | 4 A @ 30 Vdc total for Q4 to Q9                   |
| Output type                 | Transistor source                                 |
| Switching time              | 200 μs - transition off to on @ 30 Vdc            |
|                             | 500 μs - transition on to off @ 30 Vdc            |
| Maximum switching frequency | 250 Hz  |
| Status indication           | Yes, can be seen at the product's standard screen |
| Protection                  | Yes, TVS diode at all transistored outputs.       |
| Operation voltage           | 19.2 to 30 Vdc                                    |

|  | NX5101                                    |
|--|---|
| Output impedance   | $700~\text{m}\Omega$ for Q0 to Q3         |
|  | $500~\text{m}\Omega$ for Q4 to Q9         |
| Isolation  |   |
| Output to Logic Output to Inputs                             | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |
| Output to Ethernet   | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
| Outputs Q0 for Q3 to power supply                            | 2000 Vdc / 1 minute (1500 Vac / 1 minute) |
| Outputs Q4 for Q9 to power supply Output to protection Earth | It has not.                               |
|  | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |
|  | 1500 Vdc / 1 minute (1000 Vac / 1 minute) |

Table 9: Transistor Digital Output Features

#### Note:

Switching time: Time required to switch off an output, but it depends on the load. A load with low resistance results in a shorter switching time. The informed time refers to the maximum time required to deactivate an output connected to a resistive load of  $12.5 \text{ k}\Omega$  witch is the maximum admissive resistance to digital input modules according to IEC 61131.

## 5.7. Diagnostics LEDs

MODBUS TCP head (NX5100) of NX-ERA Series have one LED to indicate diagnostics (DG LED) and one LED to indicate watchdog occurrence (WD LED). More information about diagnostics LEDs can be found at Diagnostics through LEDs section.

## 5.8. Graphic Display

The graphical display of the MODBUS TCP Head is an important tool for process control, as it is possible to recognize possible error conditions, presence of components or active diagnostics through it. In addition, it is through the graphic display that all diagnostics, including the I/O modules, are displayed to the user using the OTD - One Touch Diag functionality.

The image below describes all available fields on the graphic display's main screen, including their meanings.

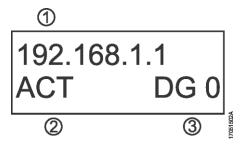


Figure 1: Graphic Display

### Legend:

- 1. IP Address
- 2. Operational State (check the Operation States section for further information)
- 3. Active diagnostics quantity indication. In case the display shows a number is different from 0 (zero) there are active diagnostics. Those may be checked by the diagnostic button OTD or through other ways described in this document.

The graphic display can also be used to configure the IP Address of the MODBUS TCP Head. For further information about the IP configuration check the section Informative and configuration Menu.

## 5.9. I/O Capacity

A MODBUS TCP Head has its capacity limited by the following values:

- Used rack model
- Consumption of each I/O module

It's important to remember that MODBUS TCP Head doesn't support bus expansion.

### 5.10. Software Features

The NX-ERA Series brings to the user the MasterTool IEC XE, a powerful tool that provides a complete interface for programming of all modules of NX-ERA Series. This means that there is no need for other software to perform the configuration of the MODBUS TCP Head. All configurations are done in the same software used for programming the NX-ERA Series CPUs.

The MODBUS TCP Head's configuration is sent by MasterTool through the Ethernet network.

## 5.11. Compatibility with Other Products

The following table provides information regarding compatibility with other NX-ERA Series products.

| NX5100              |              | NX5101              |              | Compatible Soft-<br>ware Version |
|---------------------|--------------|---------------------|--------------|----------------------------------|
| Version             | Revision     | Version             | Revision     | MasterTool IEC XE                |
| 1.0.0.5 or higher   | AC or higher | -                   | -            | 3.03 to 3.05                     |
| 1.7.17.0 or higher  | AC or higher | -                   | -            | 3.10 or higher                   |
| 1.8.11.0 or higher  | AC or higher | 1.7.40.0 or higher  | AA or higher | 3.18 or higher                   |
| 1.9.12.0 or higher  | AC or higher | 1.9.12.0 or higher  | AA or higher | 3.30 or higher                   |
| 1.12.18.0 or higher | AC or higher | 1.12.18.0 or higher | AA or higher | 3.51 or higher                   |

Table 10: Compatibility with Other Products

#### Note:

**Product Revision**: If the firmware is updated at field, the product revision indicated on tag will no longer match the real product version.

# 6. Installation

For the correct installation of this product, it is necessary to use a rack (backplane rack) and it must be carried out according to the mechanical and electrical installation instructions that follow.

## 6.1. Product Identification

Both products have some parts that must be observed before installation and use. The following figures identify each of these parts.

#### 6.1.1. NX5100

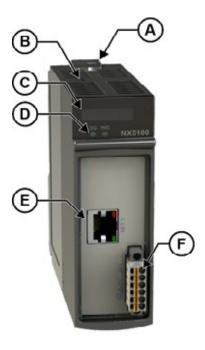


Figure 2: NX5100

- A Fixing lock.
- B Diagnostic switch.
- Status and diagnostic display.
- Diagnostic and watchdog LEDs.
- E) RJ45 connector for Ethernet communication.
- (F) Connector for power supply.

#### 6.1.2. NX5101

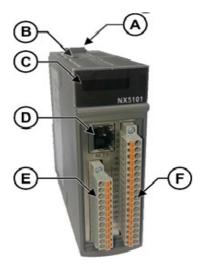


Figure 3: NX5101

- A Fixing lock.
- B Diagnostic switch.
- Status and diagnostic display.
- D RJ45 connector for Ethernet communication.
- Power supply connector, I/O and RS-485.
- F I/O connector.

The products have in their mechanics a label that identifies them and in it are presented some symbols whose meaning is described below:



Attention! Before using the equipment and installing, read the documentation.

**Direct** Current.

# 6.2. Electrical Assembly

The figures below show the NX5100 and NX5101 module's electrical diagram installed on a NX-ERA Series Rack. The connectors' disposition is merely illustrative in the figure.

#### 6.2.1. NX5100

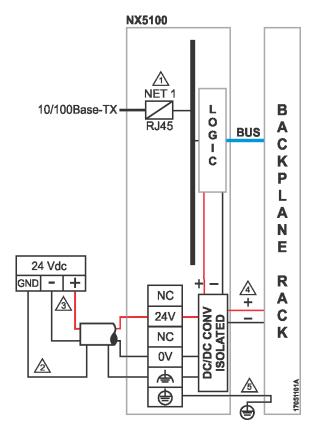


Figure 4: Electrical Diagram of the NX5100

#### Diagram Notes:

↑ Standard Ethernet interface 10/100Base-TX.

Shielding from the external power supply connection can be connected to terminal . If the grounding of the external source is the same as that of the rack, connect the terminal only to the terminal Use 0.5 mm<sup>2</sup> cables.

The power supply is connected to the terminals 24 V and 0 V. Use 0.5 mm<sup>2</sup>.

⚠ The module feeds the other modules of the NX-ERA Series through rack connection

The grounding of the module is done via the NX-ERA Series rack.

Protection earth terminal.

Functional earth terminal.

#### 6.2.2. NX5101

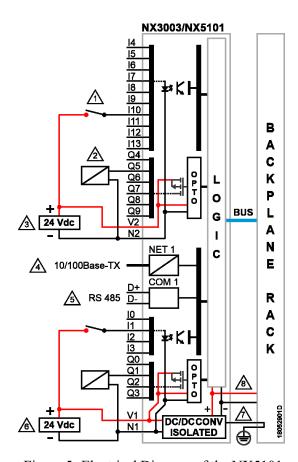


Figure 5: Electrical Diagram of the NX5101

#### Diagram Notes:

Typical usage of sink digital inputs, N2 is the 0 Vdc common to input I4 to I13.

Typical usage of source digital outputs.

**A** External power supply to supply the outputs Q4 to Q9, V2 is connected to +24 Vdc and N2 is connected to 0 Vdc.

Ethernet 10/100Base-TX standard interface.

Serial RS-485 interface (available only on NX3003). D+ and D- pins

External power supply to supply the module and outputs Q0 to Q3, V1 is connected to +24 Vdc and N1 is connected to 0 Vdc. N1 is the common 0 Vdc input group I0 to I3.

The module is grounded through the NX-ERA Series backplane racks.

The module supplies the other modules through the connection to the backplane rack.

Protection earth terminal.

# 6.3. Connector Pinout

### 6.3.1. NX5101

The following table shows descriptions for each connector terminal:

| Panel Identification | Description                |
|----------------------|----------------------------|
| D+                   | Pin D+                     |
| D-                   | Pin D-                     |
| 10                   | Input 00                   |
| I1                   | Input 01                   |
| I2                   | Input 02                   |
| I3                   | Input 03                   |
| Q0                   | Output 00                  |
| Q1                   | Output 01                  |
| Q2                   | Output 02                  |
| Q3                   | Output 03                  |
| V1                   | Power for Outputs 00 to 03 |
| N1                   | Common for Inputs 00 to 03 |

Table 11: Connector pinout - 12 positions

| Panel Identification | Description                |  |
|----------------------|----------------------------|--|
| 4                    | Input 04                   |  |
| 5                    | Input 05                   |  |
| 6                    | Input 06                   |  |
| 7                    | Input 07                   |  |
| 18                   | Input 08                   |  |
| 19                   | Input 09                   |  |
| I10                  | Input 10                   |  |
| I11                  | Input 11                   |  |
| I12                  | Input 12                   |  |
| I13                  | Input 13                   |  |
| Q4                   | Output 04                  |  |
| Q5                   | Output 05                  |  |
| Q6                   | Output 06                  |  |
| Q7                   | Output 07                  |  |
| Q8                   | Output 08                  |  |
| Q9                   | Output 09                  |  |
| V2                   | Power for Outputs 04 to 09 |  |
| N2                   | Common for Inputs 04 to 13 |  |

Table 12: Connector pinout - 18 positions

### 6.4. Protection Circuit

For further information, consult the "Lightining Protection" section of the NX-ERA Series User Manual - MU214600.

#### ATTENTION

Atmospheric discharges (thunders) may cause damages to the product although its protections. Additional protections should be used if the product's power comes from a power supply located outside the panel where it is installed because it could be vulnerable to this kind of discharges. If the field wiring of the output points is susceptible to this kind of discharge, surge suppressors should be used.

## 6.5. Mechanical Assembly

Instructions on mechanical assembly and the procedures for inserting/removing modules in the rack are described in the NX-ERA Series User Manual - MU214600. The NX510X module must be installed in position 0 of the NX-ERA Series backplane.

#### **ATTENTION**

Products with broken warranty seal are not covered in warranty.

#### CAUTION

The device is sensitive to static electricity (ESD). Always touch in a metallic grounded object before handling it.

#### DANGER

NX-ERA Series can operate with voltage up to 250 Vac. Special care must be taken during the installation, which should only be done by qualified technical personnel. Do not touch on the wiring field when in operation.

#### 6.6. Software Installation

Programming software installation instructions are described in MasterTool IEC XE Utilization Manual MU299609.

# 6.7. Physical Dimensions

## 6.7.1. NX5100

Dimensions in mm.

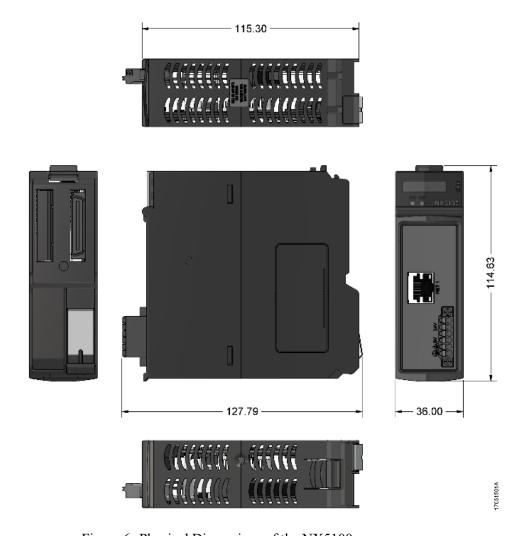


Figure 6: Physical Dimensions of the NX5100

### 6.7.2. NX5101

Dimensions in mm.

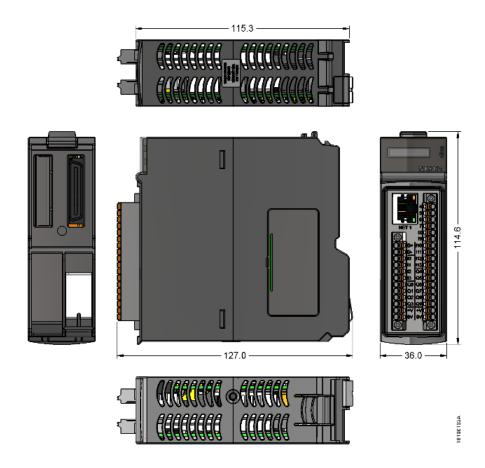


Figure 7: Physical Dimensions of the NX5101

# 7. Configuration

The configuration of the MODBUS TCP Head and its I/O modules is done by the tool MasterTool IEC XE. The network parameters of the head's Ethernet port can be either configured via web page or through the graphic display with the help of OTD button, located on the head's upside part. The procedure to configure the network parameters through the web page is described on Diagnostics through WEB section. Further configuration procedures are described on the following sections.

## 7.1. Informative and configuration Menu

The MODBUS TCP Head's Informative and Configuration Menu is accessed by a long touch on the diagnostic button from the initial status screen showed on the display. The information are organized through levels, and to access and edit a menu item it is enough to do a long touch, while a short touch allows to navigate through same level items.

The table below shows the menu levels and each item type:

| Level 1   | Level 2        | Level 3                       | Туре          |
|-----------|----------------|-------------------------------|---------------|
|           | TEMPERATURE    | -                             | Informative   |
|           | CONTRAST       | CONTRAST LEVEL                | Configurable  |
| HARDWARE  | INPUTS         | STATUS OF DIGITAL IN-<br>PUTS | Informative   |
|           | OUTPUTS        | STATUS OF DIGITAL OUTPUTS     | Informative   |
|           | BACK           | -                             | Returns Level |
|           | ENGLISH        | >ENGLISH                      | Configurable  |
| LANGUAGES | PORTUGUES      | >PORTUGUES                    | Configurable  |
|           | ESPANOL        | >ESPANOL                      | Configurable  |
|           | BACK           | -                             | Returns Level |
|           | NET 1 IP ADDR. | IP ADDRESS                    | Configurable  |
| NETWORK   | NET 1 MASK     | MASK                          | Configurable  |
|           | NET 1 GATEWAY  | GATEWAY                       | Configurable  |
|           | BACK           | -                             | Returns Level |
|           | FIRMWARE       |                               | Informative   |
| SOFTWARE  | BOOTLOADER     | -                             | Informative   |
|           | BACK           |                               | Returns Level |
| BACK      | -              | -                             | Returns Level |

Table 13: Information Menu and Configuration Levels

#### Note:

Temperature: The item "TEMPERATURE" is not available on the NX5101 head.

**Inputs and Outputs**: The hardware submenus "INPUTS" and "OUTPUTS" are only available on the NX5101 head that supports integrated I/O.

As described on the table above, among the available options for visualization and change, it is found the main required information for product utilization, like:

- Hardware resources information::
  - TEMPERATURE MODBUS TCP Head internal temperature (Ex.: 36°C 97°F)
  - CONTRAST MODBUS TCP Head frontal display contrast adjust
  - INPUTS State of the inputs integrated in the NX5101 head
  - OUTPUTS State of the outputs integrated in the head NX5101
- MODBUS TCP Head menu language changeP:
  - PORTUGUES Change the language to Portuguese

- ENGLISH Change the language to English
- ESPANOL Change the language to Spanish
- Visualization and configuration of the device network information:
  - NET 1 IP ADDR. IP Address (Ex.: 192.168.0.1)
  - NET 1 MASK Network mask (Ex.: 255.255.255.0)
  - NET 1 GATEWAY Gateway Address (Ex.: 192.168.0.100)
- Software versions information:
  - FIRMWARE MODBUS Head software version (Ex.: 1.0.0.0)
  - BOOTLOADER MODBUS Head Bootloader version (Ex.: 1.0.0.0)

The figure below describes an example of how to operate the MODBUS TCP Head's menu, performing the contrast adjustment procedure from the Status screen. Besides making the configuration easier, it's possible to identify the main levels and the touch time to navigate between them. The short touch shows that the contrast is being increased (brighter), and the next touch after the maximum value returns it to the minimum value (darker). The long touch confirms the desired contrast and returns to previous level.

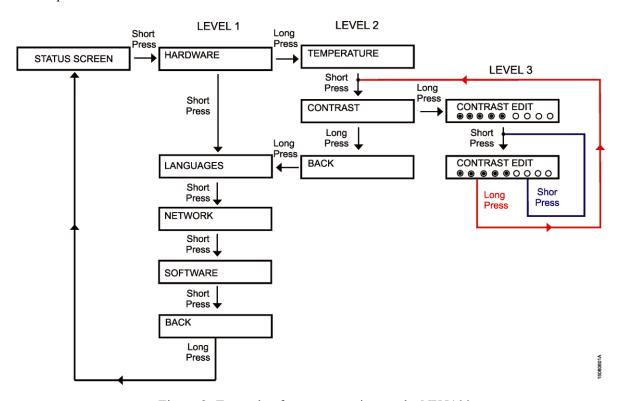


Figure 8: Example of menu operation on the NX5100

Additionally to finish the edition of MODBUS TCP Head's menu through a long press on the diagnostic button in level 1 BACK screen, there are either another exit conditions, which are described below:

- A short touch, at any moment, on the modules present at the bus, makes the head exit the menu and show the desired module diagnostics.
- Inactivity time, at any level, longer than 5s. (except monitoring the status of inputs and outputs)

## 7.2. Configuration Tool

The configuration tool MasterTool IEC XE, used to configure and program the NX-ERA Series CPUs, is also used to configure the MODBUS TCP Head. This section describes the Head configuration procedure, without repeating all information that is already on the MasterTool IEC XE utilization Manual - MU299609.

The MODBUS TCP Head configuration procedure starts by creating a new project (File > New Project...) or by opening a project created previously (File > Open Project...). When creating a new standard project, the project name and the path where its going to be stored will be asked:

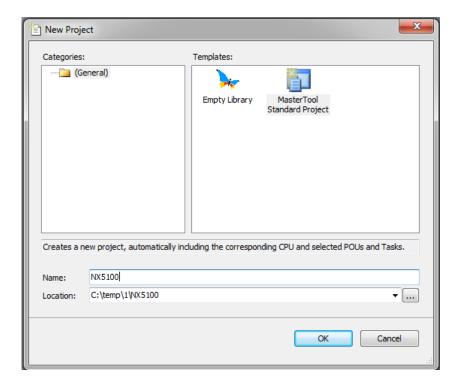


Figure 9: New Project

After confirming the information, the CPU/Head model for which the project is being developed, in this example it's the MODBUS TCP Head model NX5100, and also the rack model:

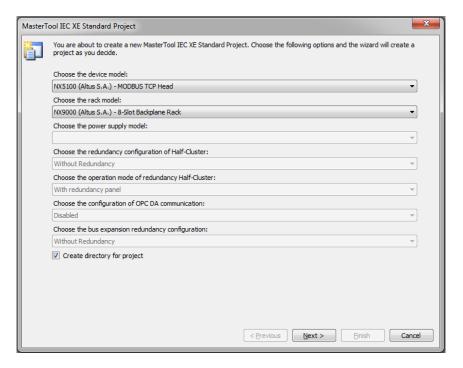


Figure 10: Device Model

On the next step the I/O modules type can be selected, NX-ERA (NX) or NX-ERA Jet (NJ), and the quantity of each type of I/O points' (digital input, digital output, Voltage/Current Input, etc...). The head doesn't support expansion racks, therefore the project is limited to a single rack. In this example we're going to define some I/O points during the project creation step, according to the following figure. After the conclusion of this step, the tool will create a project with the rack, the MODBUS head and the I/O modules according to the quantity of the selected points', according to the second figure.

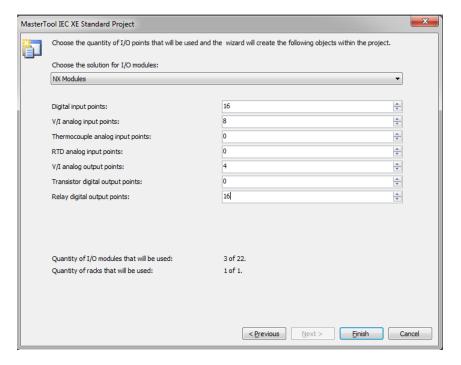


Figure 11: Solution for I/O Modules

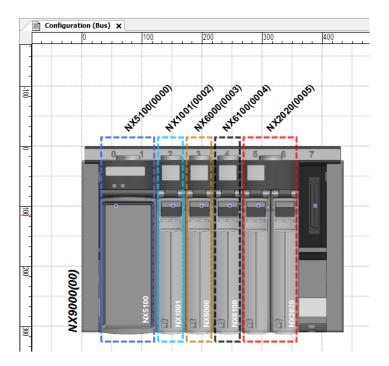


Figure 12: Configuration Bus

The "Add Modules" section of MU299609 can be consulted if is desired to insert more I/O modules on the Head bus after the project is already created. The procedure to be followed is the same as inserting I/O modules on the NX-ERA Series CPU's bus. It also is applicable to I/O modules parameters edition, the section "Module Parameters" of chapter "Editors" of MU299609 must be consulted.

After inserting the I/O modules on the bus, it is necessary to compile the project, to the project device structure be updated and to go on with the project configuration. After the compilation is finished, the GVLs and the MODBUS Symbol Server driver will be updated.

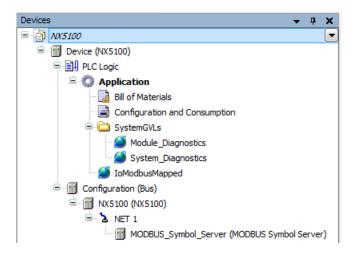


Figure 13: Devices Tree

A double click with the left mouse button over NX5100 components, on the device tree window, will open the Head parameters configuration tab, showing the following figure. On the second tab, the current consumption can be seen.

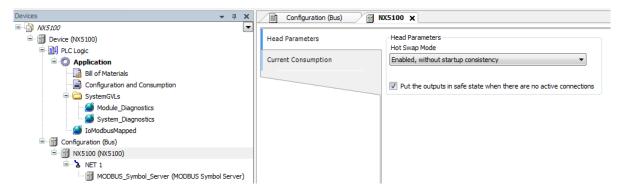


Figure 14: Parameters of the NX5100

The parameters related below are part of the Head configuration. Each item must be rightly reviewed by the user for the project correct working.

| Configuration | Description  | Factory Default                    | Possibilities  |
|---------------|--|------------------------------------|--|
| Hot Swap      | Modules hot swap mode.   | Enable, without start consistency. | Disable, for declared modules only Disabled Disabled, without consistency in the start Enable, with consistency in the start only for declared modules Enable, with consistency in the start Enabled, without consistency in the start |
| Outputs State | Set the outputs to safe state when there is no active connections. | Enable                             | Enable<br>Disable  |

Table 14: Parameters of NX5100 Head

| Configuration | Description  | Factory Default                    | Possibilities                               |
|---------------|--|------------------------------------|---|
| Hot Swap      | I/O modules hot swap mode.   | Disable, for declared modules only | Disable, for declared modules only Disabled |
|               |  |                                    | Disabled, without consistency in the start  |
| Outputs State | Set the outputs to safe state when there is no active connections. | Enable                             | Habilitado<br>Desabilitado                  |

Table 15: Parameters of NX5101 Head

The MODBUS TCP Head hot swap modes are the same supported by the NX-ERA Series CPUs. To working details, check

Hot Swap section on NX-ERA Series CPUs Utilization Manual - MU214605.

When enabled, the parameter that set the outputs to safe state when there is no active connections, will change the Head to STOP and turn off all digital and analog modules outputs when no MODBUS client is connected to it. This condition can be quickly detected by the Head when the client closes the connection or in a slower way when it detects communication time-out with the connected MODBUS clients. This communication time-out value can be changed by the user in MODBUS Symbol Server Advanced parameters.

The next adjustments to be done in Head configuration are about the MODBUS Symbol Server communication protocol inserted under the NET 1. Among the parameters are the TCP port address, connection mode (TCP or RTU over TCP), IP filter to data write/read and the two advanced parameters which define the task interval and the connection inactivity time-out. These general parameters are common to NX-ERA CPUs and their description can be found at section MODBUS Server Protocol General Parameters — Configuration via Symbolic Mapping of NX-ERA Series CPUs Utilization Manual - MU214605.

Figure 15: MODBUS Mapping

#### **ATTENTION**

The following TCP ports of Ethernet interface are used by another Head services and therefore, are reserved and must not being used by the user to configure the MODBUS TCP protocol: 80, 1217 and 11740.

MODBUS Server Head maximum protocol limits:

- Quantity of connections with clients = 64
- Quantity of simultaneous requests = 64

The MODBUS mappings showed on the previous figure can't be changed by the user. They are automatically generated by the MasterTool according to the declared modules, when the user compiles the project. Therefore every time the user add or remove an I/O module, the project must be compiled again to update the MODBUS mappings.

The MODBUS mappings must be used as reference by the user that will develop the MODBUS Client application, which will communicate with the Head. It might be observed that all data types (digital inputs, analog inputs, digital outputs, etc...) are mapped sequentially in MODBUS objects of Holding Register type:

- Inputs: from the Holding Register of address 1
- Outputs: from the Holding Register of address 10001
- Diagnostics: from the Holding Register of address 20001

By the fact that all Head mappings are always done in Holding Register type MODBUS objects, the Head supports only Holding Register reading/write MODBUS functions, according to the table presented below.

| Function Code |      |  |  |
|---------------|------|--|--|
| DEC           | HEX  | MODBUS Function Description                |  |
| 3             | 0x03 | Holding Register Reading                   |  |
| 6             | 0x06 | Holding Register Writing                   |  |
| 16            | 0x10 | Multiple Holding Registers Writing         |  |
| 22            | 0x16 | Holding Register Masked Writing            |  |
| 23            | 0x17 | Multiple Holding Registers Reading/Writing |  |

Table 16: Function Code

The order of the mappings follows the same order that the modules were declared on the bus, starting by the diagnostics, then the inputs and at last each module outputs (when they exists). Observe that the NX5100 Head only have mappings related to its diagnostics, while the NX5101 Head has three mappings, one for its diagnostics, one for its inputs and one for its outputs. A mixed module like NX1005 would have three mappings: its diagnostics (two Holding Registers), its inputs (one Holding Register) and its outputs (one Holding Register). Also, taking the NX1005 as example, it has only eight digital inputs and

eight digital outputs, being necessary only one input byte and one output byte, thus the most significant byte of each Holding Register is not used.

The NX5101 Head diagnostics format, stored in Holding Registers, can be checked at Diagnostics through MODBUS TCP protocol section. In the other hand, the modules diagnostics format follows each module's diagnostic structure pattern, the same used at the modules diagnostics GVL (Module Diagnostics) of NX-ERA CPUs applications.

The last configuration to be done by the user, before compiling again and downloading the application to the Head, is the NET 1 Ethernet network parameters. They are IP Address, Subnetwork Mask and Gateway Address. It's not possible to use DHCP on the Head, because MasterTool use this IP address to establish communication and download the application.

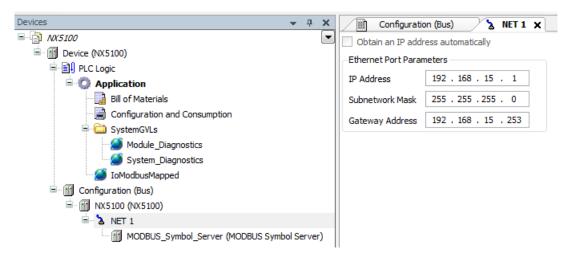


Figure 16: NET1 Configuration

IP Address parameter must be edited by the user with the same value configured on the device, because this parameter defines where MasterTool will download the application when asked for. Observe that the download procedure is slightly different from the one done on NX-ERA CPUs, where the user need to previously select a CPU, from the gateway list, to download the project. For the MODBUS TCP Head, the user don't need to configure any communication Gateway.

In case the user need to change Head's IP Address, it must be done through the web page first or through front display + OTD button, and then change the IP Address on the project to be downloaded. In case the user configures an IP address which doesn't match any device on the network, MasterTool won't be able to download the application and an error message will be shown

After finishing the configuration, it will be need to compile again the project before downloading it, and this is done automatically by the MasterTool if the Login command is executed.

After the login, it is not possible to change its state from STOP to RUN (neither it's necessary), it will automatically go to RUN when a client connects to it. The user can also choose to download the source code of the project to the Head.

It is possible to keep logged in on the Head with MasterTool to watch the system diagnostics (NX5100 diagnostics) and of its I/O modules, as well as Input/output values. It is not allowed the write or forcing of values through MasterTool on the Head.

### ATTENTION

In case of doubts about MasterTool IEC XE, MasterTool IEC XE utilization Manual (MU299609) must be consulted. In case of doubts about MODBUS TCP Head communication parameters or MODBUS Symbol Server communication driver, NX-ERA Series CPUs' Utilization Manual (MU214605) can be consulted.

## 7.3. Programming

Messung recommends the use of NX-ERA and Xtorm Series controllers to communicate with the NX510x MODBUS TCP Heads, due to programming an integration ease provided by MasterTool.

This section shows some programming details of NX-ERA Series CPU NX3030, used as a NX5100's MODBUS Client, configured on the previous section.

The first step is to create a GVL (NX5100\_example) in CPU's project, based on the Head's MODBUS mapping, whose variables are declared on Head's IoModBusMapped GVL. The suggestion is to copy the content of hat GVL and paste it on the GVL created on CPU's project, to then do the following changes:

- Change the AT direct variables address from %Q to %M, which are linked to the I/O modules and Head diagnostics. Later these variables are going to be mapped CPU's Client MODBUS driver.
- Create a structured diagnostic variable to each module, repeating the same previous AT %M address. These variables of type structure will make easy to interpret and treat the diagnostics on CPU's application. It's necessary to duplicate the diagnostics, because MasterTool doesn't accept the mapping of structure types linked to Holding Register objects on MODBUS Client driver.
- Change the digital input and output modules value variables type to WORD. Each WORD variable can store up to 16 bits of digital data and as the NX1001 and NX2020 modules owns exactly 16 bits of data, one WORD variable is enough to access all their digital inputs or outputs. Later these variables will also be mapped on CPU's MODBUS Client driver.

```
NX5100_example x
Configuration (Bus)
         VAR GLOBAL
             // NX5100
             SLOT00_NX5100_Diagnostic
                                              AT %MB15000 : ARRAY [0..7] OF WORD;
             SLOT00 NX5100 Diagnostic T
                                             AT %MB15000 : T_DIAG_TO_MODBUS_1;
             SLOT02 NX1001 Diagnostic
                                             AT %MB15016 : WORD:
             SLOT02_NX1001_Diagnostic_T
                                             AT %MB15016 : T_DIAG_NX1001_1;
             SLOT02_NX1001_Digital_Inputs
   10
             // NX6000
             SLOT03 NX6000 Diagnostic
                                             AT %MB15018 : ARRAY [0..8] OF WORD:
             SLOT03_NX6000_Diagnostic_T
                                             AT %MB15018 : T_DIAG_NX6000_1;
   13
14
15
             SLOT03_NX6000_Analog_Inputs
                                                          : ARRAY [0..7] OF INT;
             // NX6100
                                             AT %MB15036 : ARRAY [0..4] OF WORD;
             SLOT04 NX6100 Diagnostic
   16
17
18
             SLOT04_NX6100_Diagnostic_T
                                             AT %MB15036 : T DIAG NX6100 1;
             SLOT04_NX6100_Analog_Outputs
                                                         : ARRAY [0..3] OF INT;
             // NX2020
   19
             SLOT05_NX2020_Diagnostic
                                             AT %MB15046 : ARRAY [0..1] OF WORD;
   20
                                             AT %MB15046 : T_DIAG_NX2020_1;
             SLOT05 NX2020 Diagnostic T
   21
             SLOT05_NX2020_Digital_Outputs
                                                          · worn.
   22
```

Figure 17: NX5100 Example

Observe that the diagnostic variable SLOT00\_NX5100\_Diagnostic\_T created to NX51000 Head isn't of a known type to MasterTool. So as second step, it's needed to add the "NX5100 Diagnostic Structs" library to the project. The library version (1.0.0.1) might change according to MasterTool version.

The Head diagnostic structure mapped at MODBUS protocol can be consulted at section Diagnostics through MODBUS TCP protocol.

As third step it must be configured the MODBUS Server device (NX5100 Head), inserted under the CPU's MODBUS Client driver. There will be needed to map the diagnostic variables and Head's input and output value variables.

Define the inputs and diagnostics read and outputs write requests. As well as adjust the general parameters as Head's IP address, connection port, and simultaneous request maximum number and communication time-out.

On the following figures are present the mapping, request and general parameters to be adjusted.

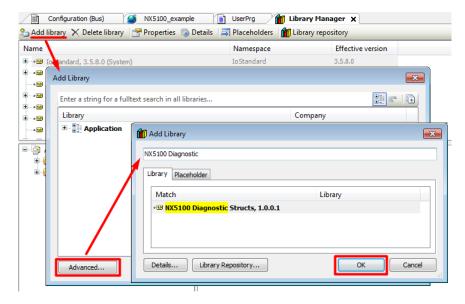


Figure 18: Adding Library to the Project

The NX5100 MODBUS Head mappings in the CPU's MODBUS Client are very similar to those created automatically by MasterTool in the Head's project, must being used the same initial addresses and total quantities. The diagnostics and input variables must be of read type (Holding Register - Read), while the output variables must be of write type (Holding Register - Write).

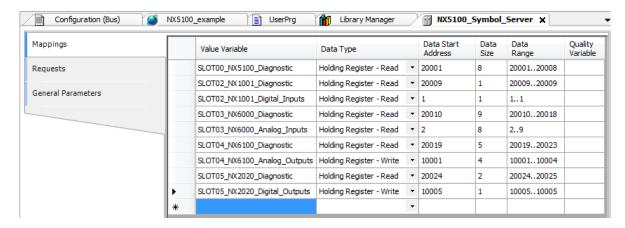


Figure 19: MODBUS Mappings

Using the MODBUS function 22, it can write the output registers and read the input registers with a single command, improving system performance. Such advantage is only possible, because both devices, Head and NX-ERA CPU, support MODBUS function 22. Observe that, Head and its modules diagnostics registers, obtained through MODBUS function 3, were configures to be updated in a lower frequency.

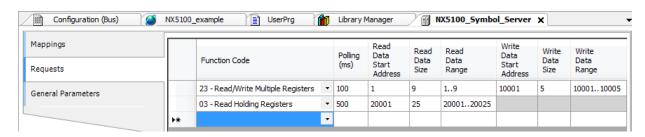


Figure 20: MODBUS Requests

To ensure that both MODBUS request are going to be executed by the MODBUS Client in the configured frequency (polling parameter), it's convenient to adjust the MODBUS Server device advanced parameter to the maximum value of two simultaneous requests.

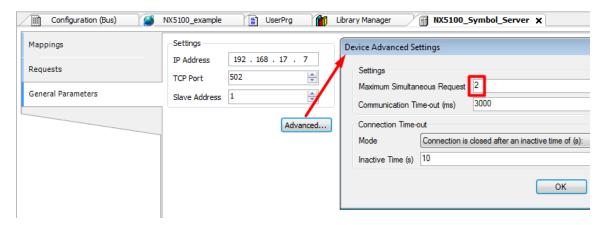


Figure 21: MODBUS General Parameters

After finished the configuration, the user just need to program the control logics according to its needs, based on the involved devices diagnostics structures, as shown below.

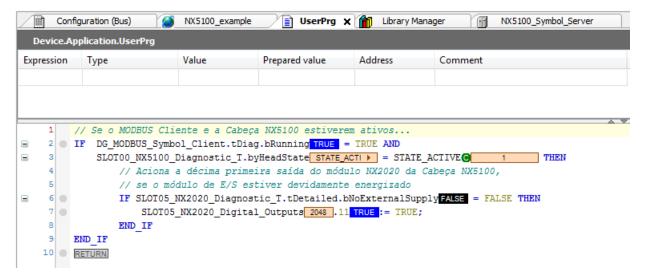


Figure 22: Control Logics

## 8. Maintenance

Messung recommends that all modules connections be checked and the dust and any kind of dirt located at the module's compartment be removed at least each 6 months.

The MODBUS TCP Head offers a series of features to help the user during the maintenance, according to the following descriptions.

### 8.1. One Touch Diag

The One Touch Diagnostics, or single touch, is an exclusive feature the NX-ERA Series brings for the programmable con-trollers. With this new concept the user can verify the diagnostics of any module connected to the system straight on the Head graphic display with a single touch on the module Diagnostic Switch. This is a powerful diagnostic tool which can be used off-line (with no need of supervisory or programming software) making easier to find and solve quickly possible problems.

The diagnostics key is placed on the Head upper part, in an easy access place and, besides giving active diagnostics, allows the access to the navigation menu, described in the Configuration section.

For further information about the OTD feature, NX-ERA Series Utilization Manual (MU214600) must be consulted.

## 8.2. Operation States

MOBUS TCP Head operation states are:

- Off-Line (OFF): In this state, the Head doesn't exchange data with the master, doesn't act on input and output devices and doesn't sweep the local I/O bus. Occurs since the moment in what the Head energized until communication establishment with master, or when there is no communication with the master.
- Ativo (ACT): In this state the Head exchanges data with the master, act on input and output devices and sweeps the local I/O bus. Can change to Offline state when lose communication with the master or to Error state when a failure is detected.
- Erro (ERR): In this state the Head doesn't update the I/O. The Head goes to this state when the hot swap is disabled and an inconsistency is found on the bus (missing modules, etc.), showing the occurred error through diagnostics. To move on from that state it's needed to reset the system (by power interruption or hot swap).
- Not-Configured (NCF): In this state the Head don't update the I/O. The Head only enter in this state when there is no configuration loaded in its memory. To move on from this state, it's needed to download a configuration on it through MasterTool.
- WRONG SLOT: In this state the head is not present on the bus, as configured in the project.

## 8.3. Diagnostics through LEDs

MODBUS TCP Head (Only NX5100) has one LED to diagnostic indication (DG LED) and one LED o watchdog indication (WD LED). The following tables explain each state of those LEDs.

### 8.3.1. DG (Diagnostic)

| Green       | Red         | Description   | Causes  | Priority   |
|-------------|-------------|---|---|------------|
| On          | Off         | MODBUS Client connected and bus operational                   | Normal operation  | 4 (Lowest) |
| Blinking 2x | Off         | MODBUS Client connected<br>and some module with<br>diagnostic | Some modules on the rack (including the head) have an active diagnostic | 3          |
| Off         | On          | MODBUS Client disconnected                                    | There is no MODBUS client connected in the Head                         | 2          |
| Off         | Blinking 1x | Configuration error or hardware rack error                    | Configuration/ Parameterization error. (check diagnostics)              | 1          |
| Off         | Blinking 4x | Installation or hardware error                                | Head inserted on the wrong slot. Rack or Head hardware failure          | 0 (Higher) |
| Off         | Off         | Without external power or head hardware error                 | External power fault. Head hardware failure.                            | -          |

Table 17: Diagnostic LED Status Description

## 8.4. WD (Watchdog)

| Green | Red         | Description                 | Causes   | Priority   |
|-------|-------------|-----------------------------|--|------------|
| Off   | Off         | Without watchdog indication | Normal operation                               | 2 (Lowest) |
| Off   | Blinking 1x | Software watchdog           | Internal software execution time overpassed 1s | 1          |
| Off   | On          | Hardware watchdog           | Module damaged                                 | 0 (Higher) |

Table 18: Watchdog LED Status Description

#### Note:

Software/hardware watchdog: To remove a watchdog indication it's necessary to reboot the device. In case that error occurs frequently, Messung technical support must be contacted.

# 8.5. Diagnostics through WEB

Besides the previously presented features, NX-ERA Series brings an innovative diagnostics and system operation states access tool, through WEB page. The utilization, besides dynamic, is much intuitive and eases the user operation. In other words, it can replace supervision systems usage when it is restricted to system status verification.

To access the MODBUS TCP Head WEB page, it's just need to use a common web browser (Internet Explores 7 or higher, Mozilla Firefox 3.0 or higher or Google Chrome 8 or higher) and type the Head IP address on the address bar (Ex.: http://192.168.15.1).

Initially, there will be presented the General Information tab which brings the MODBUS TCP Head's information.

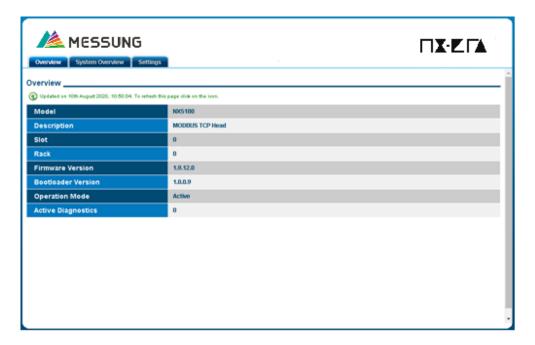


Figure 23: Overview via WEB

There is the System Overview tab, which can be visualized through Diagnostics or Status list. When to click on Diagnostics, in the same instant it is shown the MODBUS TCP Head active diagnostics.



Figure 24: Diagnostics via WEB

In case the Status tab is selected, all detailed diagnostics states are shown on the screen.

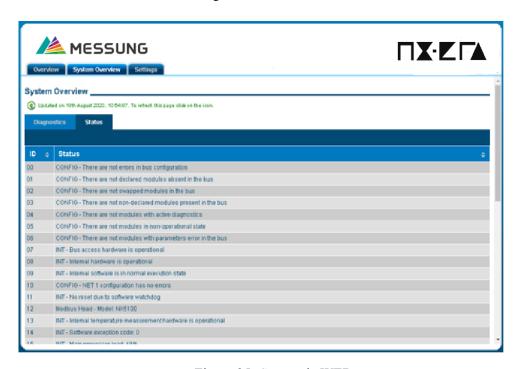


Figure 25: Status via WEB

Besides this, the user can chose between three language options: English. It's just need to select on the upper right menu the desired language.

Settings tab allows the user to configure the IP address, through the Network Configuration, where can be seen the actual configuration and a button to reset these parameters.

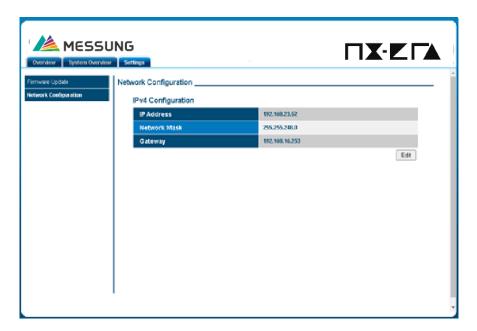


Figure 26: Network Configuration via WEB

The Firmware Update menu must only be used under Technical Support guidance.

## 8.6. Diagnostics through Variables

MODBUS TCP Head has a diagnostic structure, stored in internal memory variables, and accessible on fullness through MasterTool IEC XE, and partially available through MODBUS protocol to its clients.

The diagnostics stored in Head's internal memory are splitted in three structures:

ATTENTION

The name of the structure will depend on the model used. If a NX5100 is used, it starts with DG\_NX5100. If using a NX5101, start with DG\_NX5101.

In the structures shown below, it is being shown only from the NX5100.

- Summarized: DG\_NX5100.tSummarized structure
- Detailed: DG NX5100.tDetailed structure
- Mapped on MODBUS: DG\_NX5100.tMappedToMODBUS structure

All three structures can be accessed and visualized through MasterTool IEC XE, while logged in the Head, but only the third structure is accessible to its Clients through MODBUS protocol. This diagnostics structure mapped on MODBUS, repeats the main summarized and detailed diagnostics of the Head and it is presented at the following section.

# 8.7. Diagnostics through MODBUS TCP protocol

The Head diagnostics mapped on MODBUS protocol, are available from address 20001 of Holding Register and they fill 9 sequential address at total, as shown on the following table.

| Holding<br>Register<br>Addresses | Data Type                      | Symbolic Variable<br>DG_NX5100.<br>tMappedToMODBUS | Description                             |
|----------------------------------|--------------------------------|--|---|
| 2000120002                       | ARRAY[03] OF BYTE              | abyFirmware_Version                                | Firmware Version                        |
| 20003                            | T_DIAG_SUMMARIZED_<br>MODBUS_1 | tSummarized  | Summarized Diagnostics                  |
| 20004                            | ENUM_APP_STATE                 | byAppState   | Operation State                         |
|                                  | EN_HOT_SWAP                    | byHotSwapAndStartupStatus                          | Hot Swap and Start Up state             |
| 2000520006                       | DWORD                          | dwRackIoErrorStatus                                | I/O modules Errors                      |
| 2000720008                       | DWORD                          | dwModulePresenceStatus                             | Presence on bus of declared I/O modules |
| 20009                            | ENUM_HEAD_STATE                | byHeadState  | Head State                              |
|                                  | BYTE                           | ByReserved0  | Reserved                                |

Table 19: Head Diagnostics via MODBUS

#### Notes:

Firmware version: Heads Firmware Version. The first Holding Register stores bytes 0 and 1, while the second stores bytes 2 and 3 of the array. The byte 0 corresponds to the most significant version value. Example to firmware version 1.0.0.5:

| Holding Register | Hexadecimal Value | Decimal Value |
|------------------|-------------------|---------------|
| 20001            | 0x0100            | 256           |
| 20002            | 0x0005            | 5             |

Table 20: Firmware Version Example

Summarized Diagnostics: The summarized diagnostics also can be visualized through Head's OTD.

| HR's<br>Bit | Diagnostic Message    | Variable<br>DG_Module.tSummarized.* | Description  |
|-------------|-----------------------|-------------------------------------|--|
| 0           | HARDWARE<br>FAILURE   | bHardwareFailure                    | TRUE – Head's hardware failure.  |
|             |                       |                                     | FALSE – Hardware working fine.   |
| 1           | SOFTWARE<br>EXCEPTION | bSoftwareException                  | TRUE – One or more exceptions generated by software.                                   |
|             |                       |                                     | FALSE – No exception generated by software.  |
| 2           | NET 1 CONFIG<br>ERROR | bNET1ConfigError                    | TRUE – Some error occurred during or after configuring NET 1 Ethernet interface.       |
|             |                       |                                     | FALSE – NET 1 interface's configuration is correct.                                    |
| 3           | RUNTIME RESET         | bRTSReset                           | TRUE – The Runtime was reset at least once. This diagnostic is clean on system reboot. |
|             |                       |                                     | FALSE – Runtime is working fine.   |

| HR's<br>Bit | Diagnostic Message          | Variable DG_Module.tSummarized.* | Description   |
|-------------|-----------------------------|----------------------------------|---|
| 4           | OTD SWITCH<br>ERROR         | bOTDSwitchError                  | TRUE – OTD switch got stuck for more than 20 seconds since the last power up.               |
|             |                             |                                  | FALSE – OTD switch isn't nor was stuck.   |
| 5           | DUPLICATED<br>SLOT          | bDuplicatedSlots                 | TRUE – There are some slot addresses duplicated.  |
|             |                             |                                  | FALSE – There aren't duplicated slot addresses.   |
| 6           | -                           | bReserved_14                     | Reserved.   |
| 7           | -                           | bReserved_15                     | Reserved.   |
| 8           | CONFIG<br>MISMATCH          | bConfigMismatch                  | TRUE – There are some configurations problems on the bus. As modules on the wrong position. |
|             |                             |                                  | FALSE – The bus is configured correctly.  |
| 9           | ABSENT<br>MODULES           | bAbsentModules                   | TRUE – One or more declared modules are absent.   |
|             |                             |                                  | FALSE – All declared modules are present.   |
| 10          | SWAPED<br>MODULES           | bSwappedModules                  | TRUE – Two I/O modules are swapped between them on the bus.                                 |
|             |                             |                                  | FALSE – There are no swapped modules.   |
| 11          | NON DECLARED<br>MODULES     | bNonDeclaredModules              | TRUE – One or more I/O modules, present on the bus, aren't declared at the project.         |
|             |                             |                                  | FALSE – All present modules are declared.   |
| 12          | MODULES WITH DIAGNOSTICS    | bModulesWithDiagnostic           | TRUE – One or more I/O modules present on the bus have active diagnostics.                  |
|             |                             |                                  | FALSE – There is no module with active diagnostic.  |
| 13          | MODULES W/<br>FATAL ERROR   | bModuleFatalError                | TRUE – One or more I/O module, present on the bus, are in non functional state.             |
|             |                             |                                  | FALSE – All present modules are functional.   |
| 14          | MMODULES W/<br>PARAM. ERROR | bModuleParameterError            | TRUE – One or more I/O modules have parameterization error.                                 |
|             |                             |                                  | FALSE – All modules are parameterized.  |
| 15          | RACK ERROR                  | bWHSBBusError                    | TRUE – Master indication that there is WHSB bus failure.                                    |
|             |                             |                                  | FALSE – WHSB bus working fine.  |

Table 21: Summarized Diagnostics

Operation State: The operation state corresponds to the forth Holding Register (20004) most significant byte.

| ENUM_APP_STATE | Enumerable | Description                              |
|----------------|------------|--|
| 1              | RUN        | Input and output modules being used.     |
| 3              | STOP       | Frozen inputs and outputs in safe state. |

Table 22: Diagnosis Operating Status

Hot swap and starting state: Hot swap and starting state corresponds to the forth Holding Register (20004) less significant byte.

| EN_HOT_SWAP | Enumerable   | Description  |  |  |
|-------------|--|--|--|--|
| 00          | INITIALIZING   | Initializing, preparing to next state.   |  |  |
| 01          | RESET_WATCHDOG                                       | Not used.  |  |  |
| 02          | ABSENT_MODULES_HOT_SWAP_<br>DISABLED                 | STOP state due to Absent Modules diagnostic activation, when hot swap is configured as disable or disable only to declared modules.  |  |  |
| 03          | CFG_MISMATCH_HOT_SWAP_<br>DISABLED                   | STOP state due to Config Mismatch diagnostic activation, when hot swap is configured as disable or disable only to declared modules.   |  |  |
| 04          | ABSENT_MODULES_HOT_SWAP_<br>STARTUP_CONSISTENCY      | STOP state due to Absent Modules diagnostic activation, when hot swap is configured as enable with startup consistency or enable with startup consistency only to declared modules.  |  |  |
| 05          | CFG_MISMATCH_HOT_SWAP_<br>STARTUP_CONSISTENCY        | STOP state due to Config Mismatch diagnostic activation, when hot swap is configured as enable with startup consistency or enable with startup consistency only to declared modules. |  |  |
| 06          | APPL_STOP_ALLOWED_TO_RUN                             | STOP state and all consistency done with success. Enable to go to RUN when a MODBUS Client connects.   |  |  |
| 07          | APPL_STOP_MODULES_NOT_READY                          | STOP state and all consistency done with success. But the I/O modules are not ready to system's start. Not enable to go to RUN.  |  |  |
| 08          | APPL_STOP_MODULES_GETTING_<br>READY_TO_RUN           | STOP state and all consistency done with success. But the I/O modules are being prepared to system's start. Not enable to go to RUN.   |  |  |
| 09          | NORMAL_OPERATING_STATE                               | RUN state, in normal operation.  |  |  |
| 10          | MODULE_CONSISTENCY_OK                                | Internal use.  |  |  |
| 11          | APPL_STOP_DUE_TO_EXCEPTION                           | STOP state because an exception occurred.  |  |  |
| 12          | DUPLICATED_SLOT_HOT_SWAP_<br>DISABLED                | STOP state due to Duplicated Slot diagnostic activation, when hot swap is configured as disable or disable only to declared modules.   |  |  |
| 13          | DUPLICATED_SLOT_HOT_SWAP_<br>STARTUP_CONSISTENCY     | STOP state due to Duplicated Slot diagnostic activation, when hot swap is configured as enable with startup consistency or enable with startup consistency only to declared modules. |  |  |
| 14          | DUPLICATED_SLOT_HOT_SWAP_<br>ENABLED                 | STOP state due to Duplicated Slot diagnostic activation, when hot swap is configured as enable.  |  |  |
| 15          | NON_DECLARED_MODULE_HOT_<br>SWAP_STARTUP_CONSISTENCY | STOP state due to Non Declared Modules diagnostic activation, when hot swap is configured as enable with startup consistency.  |  |  |
| 16          | NON_DECLARED_MODULE_HOT_<br>SWAP_DISABLED            | STOP state due to Non Declared Modules diagnostic activation, when hot swap is configured as disabled.   |  |  |

Table 23: Situation Codes That Stop Application

I/O modules Errors: Each DWORD bit corresponds to a rack position.

DWORD's bit 0 corresponds to sixth Holding Register (20006) bit 0 and to rack's position zero.

DWORD's bit 16 corresponds to fifth Holding Register (20005) bit 0 and to rack's position sixteen.

Each one of the bits is an OR logic operation result between Config Mismatch (bConfigMismatch), absent modules (bAbsentModules), swapped modules (bSwappedModules), modules with fatal error (bModuleFataError) and the respective position module operational state.

I/O modules declared on bus presence Each DWORD's bit corresponds to a rack position.

DWORD's bit 0 corresponds to eighth Holding Register (20008) bit 0 and to rack's position zero.

DWORD's bit 16 corresponds to seventh Holding Register (20005) bit 0 and to rack's position sixteen.

If the respective module is present, this bit will be TRUE. It's important to remark that this diagnostic is valid to all modules except to Heads an not declared I/O modules, that is, they bus presence is not present on their respective position (bit remains FALSE).

Head State: The Head state corresponds to the ninth Holding Register (20009) most significant byte.

| ENUM_HEAD_STATE | Enumerable           | Description                           |
|-----------------|----------------------|---------------------------------------|
| 00              | STATE_OFFLINE        | SWithout MODBUS connections.          |
| 01              | STATE_ACTIVE         | In normal operation.                  |
| 02              | STATE_ERROR          | Software exception or hot swap error. |
| 03              | STATE_NON_CONFIGURED | Without loaded project.               |

Table 24: Head Condition Diagnosis

Reserved: The ninth Holding Register (20009) less significant byte is reserved for future use.

## 9. Manuals

For further technical details, configuration, installation and programming, the table below should be consulted.

The table below is only a guide of some relevant documents that can be useful during the use, maintenance, and programming of this product.

| Code     | Description                               | Language |
|----------|---|----------|
| CE114000 | NX-ERA Series – Technical Characteristics | English  |
| MU214600 | NX-ERA Series User<br>Manual              | English  |
| MU214605 | NX-ERA Series CPUs User<br>Manual         | English  |
| MU299609 | MasterTool IEC XE User Manual             | English  |
| MP399609 | MasterTool IEC XE Programming Manual      | English  |

Table 25: Related Documents